Motor controllers CMMP-AS, for servo motors





★/★ Festo core product range

Covers 80% of your automation tasks

Worldwide: Always in stock

Superb: Festo quality at an attractive price
Easy: Simplified procurement and warehousing

★ Generally ready for dispatch from the factory within 24 hours

In stock at 13 Service Centres worldwide More than 2200 products

☆ Generally ready for dispatch from the factory within 5 days Assembled for you in 4 Service Centres worldwide Up to 6 × 10¹² variants per product family

Key features

Features

Compact

- · Extremely small dimensions
- Full integration of all components for the controller and power unit, including USB interface, Ethernet and CANopen interface
- Integrated brake chopper
- Integrated EMC filters
- · Automatic actuation for a holding brake
- Compliance with the current CE and EN standards without additional external measures (→ page 6)

Motion control

- Evaluation of digital absolute encoders (EnDat/HIPERFACE) in single-turn or multi-turn versions
- Can be operated as a torque, rotational speed or position controller
- · Integrated positioning control
- Time-optimised (trapezoidal) or jerk-free (S-shaped) positioning
- · Absolute and relative movements
- · Point-to-point positioning with and without motion path smoothing
- · Position synchronisation
- · Electronic gear unit
- 255 position sets
- · Wide range of homing methods

Bus protocols















Input/output

- Freely programmable I/Os
- High-resolution 16-bit analogue input
- Jog/teach mode
- Easy connection to a higher-order controller via I/O or fieldbus
- Synchronous operation
- · Master/slave mode
- Additional I/Os with the plug-in card CAMC-D-8E8A → page 18

Integrated sequence control

- Automatic sequence of position sets without a higher-level controller
- Linear and cyclical position sequences
- · Adjustable delay times
- · Branches and wait positions
- Overlapping restart possible during the movement

Integrated safety functions

- Depending on the variant or plug-in card, the motor controller supports the following safety functions:
 - Safe torque off (STO)
 - Safe stop 1 (SS1)
 - Safe brake control (SBC)
 - Safe operating stop (SOS)
 - Safe stop 2 (SS2)
 - Safely limited speed (SLS)
 - Safe speed range (SSR)
 - Safe speed monitor (SSM)

Interpolating multi-axis movement

 With a suitable controller, the CMMP-AS can perform path movements with interpolation via CANopen or EtherCAT. To do this, the controller specifies setpoint position values in a fixed time pattern. In between, the servo position controller independently interpolates the data values between two interpolation points.

Key features

Motion program

- · Linking of any number of position sets into a motion program
- Step enabling conditions for the motion program possible via digital inputs, for example

MC - motion complete

I/O - digital inputs

Library for EPLAN

→ www.festo.com/eplan



EPLAN macros for fast and reliable planning of electrical projects in combination with motor controllers, motors and cables. This enables a high level of planning reliability and standardisation of documentation without the need to create symbols, graphics and master data.

Cam disc functionality

The "electronic cam disc" application type creates optimised motion profiles that generate less vibration and lower acceleration forces at the machine. In addition, the movement of the motor is always synchronised with the position of a master axis so that overlapping, time-optimised motion sequences can be easily defined. To be able to use the cam disc function, you will need the Festo Configuration Tool (FCT) and also the cam editor → Page 4.

Key features:

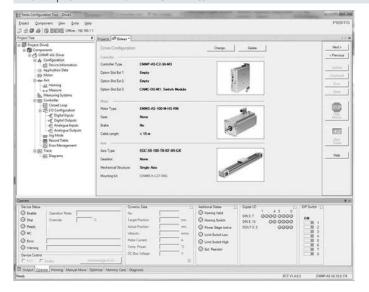
- High flexibility of the system. The mechanical system does not need to be modified if the requirements for the cam shapes change.
- User-friendly motion plan editor. All limits for position, speed and acceleration
 are immediately displayed in the editor. Up to 16 cam discs with a total of up
 to 2048 interpolation points can be managed. The interpolation points can be
 randomly distributed along the cam discs.
- There are four digital trip cams coupled with each cam disc.
- Each cam disc can be offset by a certain amount from the master axis.

ePLAN® is a registered trademark of its respective trademark holder in certain countries.

Key features

FCT software - Festo Configuration Tool

Software platform for electric drives from Festo



- All drives in a system can be managed and saved in a common project
- Project and data management for all supported types of equipment
- Easy to use thanks to graphically supported parameter entry
- Universal mode of operation for all drives
- Work offline at your desk or online at the machine

FHPP - Festo Handling and Positioning Profile

Optimised data profile

Festo has developed an optimised data profile, the "Festo Handling and Positioning Profile (FHPP)", which is specifically tailored to handling and positioning applications.

With the FHPP data profile, Festo motor controllers can be controlled using a fieldbus interface via standardised control and status bytes.

The following are defined, among others:

- Operating modes
- I/O data structure
- Parameter objects
- Sequence control

Product range overview and type codes

Туре	CMMP-ASMO	CMMP-ASM3				
Bus protocols						
Integrated in the controller						
CANopen	•	•				
Modbus TCP	•	•				
Optional via plug-in card						
PROFIBUS DP	-	•				
DeviceNet	-	•				
EtherCAT	-	•				
EtherNet/IP	-	•				
PROFINET RT	-	•				
Safety functions						
Integrated in the controller	•	-				
Optional via plug-in card	-	•				

Type codes

001	Series	
СММР	Motor controller, premium	
002	Motor type	
AS	AC synchronous	
003	Nominal current	
C2	2 A	
C5	5 A	
C10	10 A	
C15	15 A	

004	Nominal input voltage	
3A	230 V AC/50-60Hz	
11A	400 V AC	
005	Number of phases	
	Single-phase	
P3	Three-phase	
006	Number of slots	
006 M0	Number of slots Without slots	

Bus protocols













Modbus





General technical data							
CMMP-AS-		C2-3A	C5-3A	C5-11A-P3	C10-11A-P3	C15-11A-P3	
Type of mounting	Screwed onto co	Screwed onto connection plate					
Display	Seven-segment	display					
Parameterisation interface		USB, Ethernet					
Active PFC		Yes		-			
DIP switch		Firmware down	load/fieldbus settings ¹	¹⁾ /CAN terminating resisto	r		
SD card slot		Memory card →	page 19			'	
Encoder interface input		Resolver					
		Incremental en	coder with analogue or	digital tracking signals			
		Absolute encod	er with EnDat V2.1 ser	ial/V2.2			
		Absolute encod	er with HIPERFACE				
		Additional inpu	t for synchronous/cam	disc operation			
Encoder interface output		Actual value fee	dback via encoder sigr	nals in rotational speed co	ontrol mode	,	
		Setpoint specifi	Setpoint specification for downstream slave drive				
		Resolution up to	Resolution up to 16384 ppr				
Braking resistor, integrated	$[\Omega]$	60		68			
Pulse power of braking resistor	[kVA]	2.8		8.5			
Braking resistor, external	[Ω]	≥ 50		≥ 40			
Impedance of setpoint input	$[k\Omega]$	20					
Number of analogue outputs		2					
Operating range of analogue outputs	[V]	±10					
Resolution of analogue outputs		9 bit	9 bit				
Characteristics of analogue outputs		Short-circuit-pro	oof				
Number of analogue inputs		3					
Operating range of analogue inputs	[V]	±10					
Characteristics of analogue inputs			1x differential, resolution 16 bit				
		2x single-ended, resolution 10 bit					
		Configurable for rotational speed setpoint value/torque setpoint value/position setpoint value					
Mains filter		Integrated				External ²⁾	
Max. motor cable length ³⁾	[m]	25				-	
Product weight	[g]	2100	2200	3800		3450	

¹⁾ Not in combination with CMMP-AS-...-M0

Without external mains filter

Function blocks for PLC programming								
Programming software	Controller manufacturer	Interfaces						
		CANopen	PROFIBUS DP	DeviceNet	EtherCAT	EtherNet/IP	PROFINET RT	
CODESYS	Festo	•	•	-	•	-	-	
TwinCAT	Beckhoff							
	Other manufacturers							
RSLogix5000	Rockwell Automation	-	-	•	-	•	_	
Step 7/TIA Portal	Siemens	-	•	_	_	_	•	

²⁾ The mains filter is mandatory for compliance with the CE and EN standards ightarrow page 21

Technical data – Bus protocols/contro	ol									
Interfaces		I/O	Additional I/O ¹⁾	CANopen	Modbus TCP	PROFIBUS DP	DeviceNet	EtherCAT	EtherNet/IP	PROFINET RT
Number of digital logic outputs		5	8	5						
Characteristics of digital logic outputs		Freely config	gurable							
Number of digital logic inputs		10	8	10				-		
Characteristics of logic inputs		Freely config	gurable							
Process interfacing		16 (127) position sets ²⁾	255 position sets	250 positio	n sets					
Communication profile		-	-	DS301; FHPP+	FHPP+	DP-V0/ FHPP+	FHPP+	DS301; FHPP+	FHPP+	FHPP+
				DS301; DSP402				CoE: DS301; DSP402		
Max. fieldbus transmission rate	[Mbps]	-	-	1	100	12	0.5	100	100	100
Interface			•	•	•	•	•	•	•	
CMMP-ASM0	Integrated	•	-		•	-	-	-	-	-
CMMP-ASM3	Integrated	•	-	•		-	-	-	-	-
•	Optional ³⁾	-	•	_	-	•	•	•	•	•

¹⁾ With the plug-in card CAMC-D8E8A → page 18

³⁾ Plug-in cards can be ordered separately → page 18

Electrical data						
CMMP-AS-		C2-3A	C5-3A	C5-11A-P3	C10-11A-P3	C15-11A-P3
Output connection data						
Output voltage range	[V AC]	3x 0 270		3x 0 360		
Nominal current	[A _{eff}]	2.5	5	5	10	15
Peak current	[A _{eff}]	5	10	10	20	30
at max. peak current duration	[s]	5				
	[A _{eff}]	10	20	20	40	45
	[s]	0.5				1
Max. DC link voltage	[V DC]	320/380 ¹⁾		560		
Output frequency	[Hz]	0 1000	01000			
Load supply						
Nominal voltage phases		1		3		
Input voltage range	[V AC]	100 230 ±10%	Ď	3x 230 480 ±10%		
Max. nominal input current	[A]	3	6	5.5	11	13
Nominal power	[VA]	500	1000	3000	6000	9000
Peak power	[VA]	1000	2000	6000	12000	18000
Mains frequency	[Hz]	50 60				
Logic supply						
Nominal voltage	[V DC]	24 ±20%				
Nominal current	[A]	0.55/2.05 ²⁾	0.65/2.15 ²⁾	1/3.52)		
Max. current of digital logic outputs	[mA]	100		•		

¹⁾ Without PFC/with PFC

²⁾ Can be extended with configurable logic inputs up to max. 127 position sets

²⁾ Max. current with brake and I/Os

Safety functions to EN 61800-5-2							
Motor controller	CMMP-AS-	CMMP-AS-					
	C2/C5/C10M0	C2/C5/C10/C15M3					
With plug-in card	-	CAMC-G-S1	CAMC-G-S3				
		→ Page 14	→ Page 15				
Safe torque off (STO)	-	-					
Safe stop 1 (SS1)	-	-	•				
Safe brake control (SBC)	•	•	•				
Safe operating stop (SOS)	-	-	•				
Safe stop 2 (SS2)	-	-	•				
Safely limited speed (SLS)	-	-	•				
Safe speed range (SSR)	-	-	•				
Safe speed monitor (SSM)	-	-	•				

Safety data				
CMMP-AS-	C2/C5/C10M0			
Safety function to EN 61800-5-2	Safe torque off (STO)			
Performance Level (PL) to EN ISO 13849-1	Category 4, Performance Level e			
Safety Integrity Level (SIL) to EN 61800-5-2, EN 62061,	SIL 3			
EN 61508				
Certificate issuing authority	German Technical Control Board (TÜV) 01/205/5162.02/19			
Proof test interval	20a			
Diagnostic coverage [%]	97			
Safe failure fraction (SFF) [%]	99.2			
Hardware fault tolerance	1			
CE marking (see declaration of conformity)	To EU EMC Directive ¹⁾			
	To EU Machinery Directive			

¹⁾ For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp → Certificates.

If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

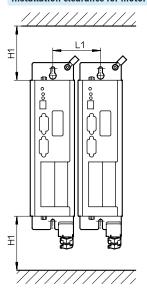
Technical data – Connection to the integrated safety module with CMMP-ASM0				
Control input STO-A/STO-B				
Nominal voltage	[V DC]	24 (related to 0V-A/B)		
Operating range	[V]	19.2 28.8		
Nominal current	[mA]	20 (typical; max. 30)		
Starting current	[mA]	450 (typical, duration approx. 2 ms; max. 600 at 28.8 V)		
Max. positive test pulse length with logic 0	oositive test pulse length with logic 0 [ms] 0.3 (related to nominal voltage 24 V and intervals > 2 s between pulses)			
Max. allowable time for test pulses at 24 V	[ms]	<26		
signal				
Key features		Galvanically isolated		
Monitoring contact C1, C2				
Nominal voltage	[V DC]	24		
Max. voltage	[V DC]	< 30 (overvoltage-resistant up to 60 V)		
Nominal current [mA]		< 200 (not short-circuit-proof)		
Design		Potential-free signal contact		
Switching logic		Contact closes at STO		

Operating and environmental conditi	ions							
CMMP-AS-		C2-3A	C5-3A	C5-11A-P3	C10-11A-P3	C15-11A-P3		
Digital logic outputs		Galvanically isol	ated					
Logic inputs		Galvanically isol	ated					
Degree of protection								
With plug at X6 and X9		IP20						
Without plug at X6 and X9		IP10						
Protective function		I ² t monitoring						
		Intermediate cire	Intermediate circuit over/undervoltage					
		Output stage sh	Output stage short circuit					
		Standstill monit	Standstill monitoring					
		Temperature mo	nitoring					
Ambient temperature	[°C]	0 +40						
Storage temperature	[°C]	-25 +70						
Relative humidity	[%]	0 90 (non-con	densing)					
CE marking (see declaration of conforr	mity)	To EU Low Voltag	ge Directive					
		To EU EMC Direct	To EU EMC Directive ¹⁾					
		To EU Machinery	To EU Machinery Directive					
Certification		c UL us listed (O	c UL us listed (OL)					
		RCM compliance	RCM compliance mark					
PWIS conformity		VDMA24364 zor	VDMA24364 zone III					
Note on materials		RoHS-compliant						

¹⁾ For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp → Certificates.

If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

Installation clearance for motor controller

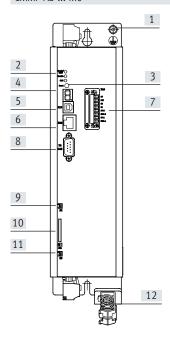


Туре	H1 ¹⁾	L1
CMMP-AS-C2-3A CMMP-AS-C5-3A	100	71
CMMP-AS-C5-11A-P3 CMMP-AS-C10-11A-P3 CMMP-AS-C15-11A-P3	100	85

¹⁾ An installation clearance of 150 mm is recommended for optimum wiring of the motor or encoder cable on the underside of the motor controller

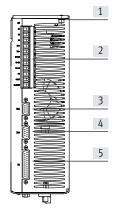
View of motor controller

CMMP-AS-...-M0



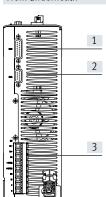
- [1] PE connection
- [2] LEDs
- [3] Reset button
- [4] Seven-segment display
- [5] X19 USB interface
- [6] X18 Ethernet interface
- [7] X40 digital I/O interface for controlling the STO function
- [8] X4 CANopen interface
- [9] Activation of CANopen terminating resistor
- [10] SD/MMC card slot
- [11] Activation of firmware download
- [12] Shield connection

From above



- [1] PE connection
- [2] X9 power supply
- [3] X11 incremental encoder interface (output)
- [4] X10 incremental encoder interface (input)
- [5] X1 I/O interface

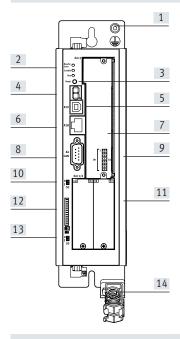
From underneath



- [1] X2B encoder connection
- [2] X2A resolver connection
- [3] X6 motor connection

View of motor controller

CMMP-AS-...-M3



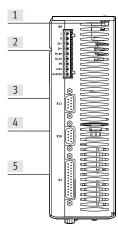
- [1] PE connection
- [2] LEDs
- [3] Reset button
- [4] Seven-segment display
- [5] X19 USB interface
- [6] X18 Ethernet interface
- [7] Slot for switch or safety module
- [8] X4 CANopen interface
- [9] Fieldbus settings
- [10] Activation of CANopen terminating resistor
- [11] Slots for extension modules
- [12] SD/MMC card slot
- [13] Activation of firmware download
- [14] Shield connection

- 🖣 - Note

One of the plug-in cards must be inserted in slot [7] in order to operate the motor controller.

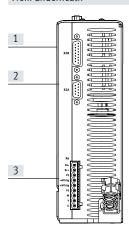
Possible plug-in cards: CAMC-DS-M1 → page 19 CAMC-G-S1 → page 14 CAMC-G-S3 → page 15

From above



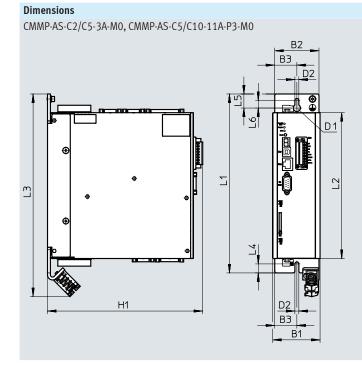
- [1] PE connection
- [2] X9 power supply
- [3] X11 incremental encoder interface (output)
- [4] X10 incremental encoder interface (input)
- [5] X1 I/O interface

From underneath



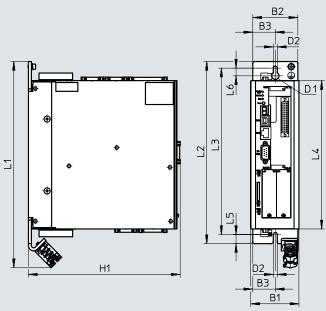
- [1] X2B encoder connection
- [2] X2A resolver connection
- [3] X6 motor connection

Download CAD data → www.festo.com



Туре	B1	B2	В3	D1 Ø	D2 Ø	H1	L1	L2	L3	L4	L5	L6	
CMMP-AS-C2-3A-M0	66	61	30.7	10	5.5	215	248	202	281	12.5	19.5	10.5	
CMMP-AS-C5-3A-M0													ĺ
CMMP-AS-C5-11A-P3-M0	79	75	37.5	10	5.5	255	297	252	330	12.5	19.8	10.5	l
CMMP-AS-C10-11A-P3-M0													





Туре	B1	B2	B3	D1 Ø	D2 Ø	H1	L1	L2	L3	L4	L5	L6
CMMP-AS-C2-3A-M3 CMMP-AS-C5-3A-M3	66	61	30.7	10	5.5	207	281	248	227	202	12.5	10.5
CMMP-AS-C5-11A-P3-M3 CMMP-AS-C10-11A-P3-M3 CMMP-AS-C15-11A-P3-M3	79	75	37.5	10	5.5	247	330	297	276	252	12.5	10.5

☆ Core product range

Ordering data			
	Description	Part no.	Туре
CMMP-ASM0 - Without slot			
1	The plug assortment NEKM (→ page 20) is included in the scope of delivery of	1622901	CMMP-AS-C2-3A-M0
	the motor controller.	1622902	CMMP-AS-C5-3A-M0
		1622903	CMMP-AS-C5-11A-P3-M0
		1622904	CMMP-AS-C10-11A-P3-M0
CMMP-ASM3 – With 3 slots			
1	One of the plug-in cards must be inserted in slot [7] (→ page 11) in order	☆ 1501325	CMMP-AS-C2-3A-M3
	to operate the motor controller.	☆ 1501326	CMMP-AS-C5-3A-M3
	Possible plug-in cards:	☆ 1501327	CMMP-AS-C5-11A-P3-M3
	- CAMC-DS-M1 → page 19	☆ 1501328	CMMP-AS-C10-11A-P3-M3
	- CAMC-G-S1 → page 14	3215473	CMMP-AS-C15-11A-P3-M3
-	- CAMC-G-S3 → page 15		
	• The mains filter is mandatory with CMMP-AS-C15 for compliance with the CE		
	and EN standards (\rightarrow page 21).		
	 The plug assortment NEKM (→ page 20) is included in the scope of delivery of the motor controller. 		

Safety module CAMC-G-S1

Only for motor controller: CMMP-AS-...-M3

The safety module serves as an extension to achieve the safety function:

• Safe torque off (STO)



Safety data				
Safety function to EN 61800-5-2		Safe torque off (STO)		
Performance Level (PL) to EN ISO 13849-1		Category 4, Performance Level e		
Safety Integrity Level (SIL) to EN 61800-5-	2, EN 62061,	SIL3		
EN 61508				
Certificate issuing authority		German Technical Control Board (TÜV) 01/205/5165.02/19		
Proof test interval		20a		
PFH		1.27×10^{-10}		
Diagnostic coverage	[%]	97		
Safe failure fraction (SFF)	[%]	99.2		
Hardware fault tolerance		1		
CE marking (see declaration of conformity)		To EU EMC Directive ¹⁾		
		To EU Machinery Directive		

¹⁾ For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp → Certificates.

If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

Technical data						
Control input STO-A/STO-B	Control input STO-A/STO-B					
Nominal voltage	[V DC]	24 (related to OV-A/B)				
Operating range	[V]	19.2 28.8				
Nominal current	[mA]	20 (typical; max. 30)				
Max. positive test pulse length with logic 0	[ms]	0.3 (related to nominal voltage 24 V and intervals > 2 s between pulses)				
Max. allowable time for test pulses at 24 V	[ms]	< 2 6				
signal						
Key features		Galvanically isolated				
Monitoring contact C1, C2						
Nominal voltage	[V DC]	24				
Max. voltage	[V DC]	< 30 (overvoltage-resistant up to 60 V)				
Nominal current	[mA]	< 200 (not short-circuit-proof)				
Design		Potential-free signal contact				
Switching logic		Contact closes at STO				

Ordering data – Plug-in card			
	Description	Part no.	Туре
	Safety module: • One of the plug-in cards CAMC-G-S1, CAMC-G-S3 or CAMC-DS-M1 must be inserted in slot [7] (→ page 11) in order to operate the motor controller. • The plugs are included in the scope of delivery. To reorder plug NEKM → page 20	☆ 1501330	CAMC-G-S1

Festo core product range	*	Generally ready for dispatch from the factory within 24 hours			
	*	Generally ready for dispatch from the factory within 5 days			

Safety module CAMC-G-S3

Only for motor controller: CMMP-AS-...-M3

The safety module serves as an extension to achieve the safety functions:

- Safe torque off (STO)
- Safe stop 1 (SS1)
- Safe brake control (SBC)
- Safe operating stop (SOS)
- Safe stop 2 (SS2)
- Safely limited speed (SLS)
- Safe speed range (SSR)
- Safe speed monitor (SSM)



Safety data				
Safety function to EN 61800-5-2	Safe torque off (STO)			
	Safe stop 1 (SS1)			
	Safe brake control (SBC)			
	Safe operating stop (SOS)			
	Safe stop 2 (SS2)			
	Safely limited speed (SLS)			
	Safe speed range (SSR)			
	Safe speed monitor (SSM)			
Performance Level (PL) to EN ISO 13849-1	Up to category 4, Performance Level e			
Safety Integrity Level (SIL) to EN 61800-5-2, EN 62061,	SIL 3			
EN 61508				
Certificate issuing authority	German Technical Control Board (TÜV) 01/205/5165.02/19			
Proof test interval	20a			
PFH	9.5×10^{-9}			
Diagnostic coverage [%]	97.5			
Safe failure fraction (SFF) [%]	99.5			
Hardware fault tolerance	1			
CE marking (see declaration of conformity)	To EU EMC Directive ¹⁾			
	To EU Machinery Directive			

¹⁾ For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp → Certificates.

If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

Technical data		
General		
Parameterisation		Using SafetyTool, integrated into the FCT plug-in for CMMP-AS
Digital safe inputs DIN 40A/B to DIN 43	BA/B	
Specification		IEC 61131-2, type 3
Number of 2-channel inputs		4
Nominal voltage	[V DC]	24
Operating range	[V]	-3 30
Nominal current	[mA]	15
Max. nominal current	[mA]	200
Key features		Suitable for emergency-stop switchgear, protective door circuit, light curtain, enabling button,
		two-hand operator unit;
		Inputs switching equivalently/antivalently;
		Test pulses can be configured;
		Function can be configured
Digital safe inputs DIN 44 to DIN 49		
Specification		IEC 61131-2, type 3
Number of 1-channel inputs		6
Nominal voltage	[V DC]	24
Operating range	[V DC]	-3 30
Nominal current	[mA]	15
Max. nominal current	[mA]	200
Key features		Suitable for start button, brake feedback, mode selector, error acknowledgement, restart blocking;
		Test pulses can be configured;
		Function can be configured
Digital safe outputs DOUT 40A/B to 42A	A/B	
Number of 2-channel outputs		3
Output		High-side switch with pull-down
Nominal voltage	[V DC]	24
Operating range	[V DC]	18 30
Permissible output current	[mA]	< 50
Key features		Semiconductor outputs: parameterisable PNP (positive switching)
		Outputs switching equivalently/antivalently
		Test pulses can be configured
		Function can be configured
Monitoring contact C1, C2		,
Nominal voltage	[V DC]	24
Max. voltage	[V DC]	< 30 (overvoltage-resistant up to 60 V)
Nominal current	[mA]	< 200 (not short-circuit-proof)
Design		Potential-free signal contact
Key features		Suitable for the diagnostics of safety functions
		Function can be configured

Supported position encoders

- Resolver via X2A
- SIN/COS incremental encoder
- SICK Hiperface shaft encoder (only process data channel)

The manufacturers of SIL-certified shaft encoders publish guidelines for their use in safety applications.

- · Heidenhain EnDat encoder
- Incremental encoder with digital A/B signals

The safety module CAMC-G-S3 takes the following manufacturer specifications into account when evaluating the encoder signals:

- BISS position sensors for linear motors
- Incremental encoder with digital A/B signals
- Implementation Manual HIPER-FACE® Safety dated 21.12.2010 (801412 0/2010-12-21)
 - → www.sick.com
- Specification of the E/E/PES safety requirements for EnDat Master dated 19.10.2009 (D533095-04-G-01)
 - → www.heidenhain.de (in preparation)

Permissible combinations of position encoders						
First encoder	Second encoder	Achievable safe	ty level	Note		
Resolver	Other encoder	SIL 3	Cat. 3/PL d; Cat. 3/ PL e	-		
Resolver	Incremental encoder	SIL 3	Cat. 4/PL e	-		
Resolver	None	SIL 2	Cat. 3/PL d	Please see the note below		
SIN/COS incremental encoder	None	SIL 3	Cat. 3/PL d	Requires SIL classification of the encoder		
SIN/COS incremental encoder	Incremental encoder	SIL 3	Cat. 4/PL e	Please see the note below		
Hiperface incremental encoder	Incremental encoder	SIL 3	Cat. 3/PL e	Please see the note below		
Hiperface incremental encoder	None	SIL 2 or 3	Cat. 3/PL d; Cat. 4/ PL e	Requires SIL classification of the encoder		
EnDat encoder	Incremental encoder	SIL 3	Cat. 4/PL e	Encoder setting: "Other encoder" Please see the note below		
EnDat encoder	None	SIL 2	Cat. 3/PL d	In preparation. Requires SIL classification of the encoder		
Other encoder	Incremental encoder	SIL 2	Cat. 3/PL d	-		



Note

- Please check whether your selected position encoder is sufficiently accurate to fulfil the monitoring task, in particular the SOS safety function.
- In applications with only one shaft encoder/position encoder, it must have the SIL classification required in accordance with the risk assessment. In most cases, the classification requires additional requirements or fault exclusions in the mechanical system. Please check carefully that these requirements are fulfilled in your application and that the appropriate fault exclusions can be performed.
- In applications with only one shaft encoder/position encoder with analogue signal interface (resolver, SIN/COS, Hiperface, etc.), the restrictions on diagnostic coverage as well as the restrictions on the achievable accuracy of standstill and speed monitoring must be taken into account.
- When using two functional encoders without SIL classification, the suitability of the encoder combination for use in safe systems up to SIL3 must be proven separately (for example, the following are required: diversity of the encoder systems with regard to CCF, MTTFd, etc., suitability of the encoders for the operating and ambient conditions, EMC, etc.).

Ordering data – Plug-in card			
	Description	Part no.	Туре
	Safety module: One of the plug-in cards CAMC-G-S1, CAMC-G-S3 or CAMC-DS-M1 must be inserted in slot [7] (→ page 11) in order to operate the motor controller. The plugs are included in the scope of delivery. To reorder plug NEKM → page 20	☆ 1501331	CAMC-G-S3

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simultaneously.

Interface CAMC-D-8E8A

Only for motor controller:

The interface is used to extend the digital I/Os. Up to two interfaces are supported





Technical data		
General		
Max. connection cross-section	[mm ²]	0.5
Electrical connection		Screw terminal
		Straight plug
Digital inputs		
Number		8
Nominal voltage	[V DC]	24
Voltage range	[V]	-30 +30 (protected against reverse polarity and short-circuit-proof)
Nominal value for True	[V]	8
Nominal value for False	[V]	2
Input impedance	$[k\Omega]$	4.7
Digital outputs		
Number		8
Nominal voltage	[V DC]	24
Voltage range	[V]	+18 +30 (protected against reverse polarity and short-circuit-proof, protection in the event of thermal overload)
Output current	[mA]	100
Short circuit, overcurrent protection	[mA]	500

Ordering data - Plug-in card					
	Description	Part no.	Туре		
	Interface: for additional I/Os (The plugs are included in the scope of delivery. To reorder plug NEKM → page 20)	567855	CAMC-D-8E8A		

Ordering data – Plug-in card			
	Description	Part no.	Туре
	Switch module: • One of the plug-in cards CAMC-G-S1, CAMC-G-S3 or CAMC-DS-M1 must be inserted in slot [7] (→ page 11) in order to operate the motor controller CMMP-ASM3.	☆ 1501329	CAMC-DS-M1

ering data – Plug-in o	ards for bus protocols			
	Description		Part no.	Туре
	For PROFIBUS DP		☆ 547450	CAMC-PB
	For PROFINET RT		☆ 1911916	CAMC-F-PN
	For DeviceNet		547451	CAMC-DN
	For EtherCAT		☆ 567856	CAMC-EC
	For EtherNet/IP		☆ 1911917	CAMC-F-EP
dering data – Memory	card			
dering data memory	Description		Part no.	Туре
	Memory card,		☆ 1436343	CAMC-M-S-F10-V1
	for data backup and firmware download		7 1750575	Crane m 3 110 VI
dering data – Connecti	on options from I/O interface to the controller	1611 11 11	l n.	I _T
	Description	Cable length [m]	Part no.	Туре
		[III]		
ntrol cable	FullOit of the controller	125	552257	NEDC CACOE I/ O E N LEO/
	For I/O interface to any controller Recommended for analogue signals since the cable is shielded	2.5	552254	NEBC-S1G25-K-2.5-N-LE26
	* Recommended for analogue signals since the cable is sinelided			
55				
	- Faul/O interferente autoritarillar	2.2	A 0001272	NEDC C4C3F V 2 2 N 1F3F
	For I/O interface to any controller Cannot be used if the incremental encoder interface (plug X10) is in	3.2	☆ 8001373	NEBC-S1G25-K-3.2-N-LE25
	use			
	use			
nnection block				
	Ensures simple and clear wiring. The connection to the motor controller	-	8001371	NEFC-S1G25-C2W25-S7
	is established via the connecting cable NEBC-S1G25-K			
The state of the s				
nnecting cable				
	Connects the motor controller to the manifold block.	1.0	8001374	NEBC-S1G25-K-1.0-N-S1G25
	Cannot be used if the incremental encoder interface (input) is in use	2.0	8001375	NEBC-S1G25-K-2.0-N-S1G25
5.0			8001376	NEBC-S1G25-K-5.0-N-S1G25
ıg				
<u>-</u>	25-pin Sub-D plug. Each single core can be individually assembled	_	☆ 8001372	NEFC-S1G25-C2W25-S6
	using screw terminals.			
	Cannot be used if the incremental encoder interface (input) is in use			

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Ordering data – Cables		Cable length	Part no.	Time
	Description	[m]	Pail IIU.	Туре
		[III]		
Programming cable				
	For CMMP-ASM0, CMMP-ASM3	1.8	1501332	NEBC-U1G4-K-1.8-N-U2G4
incoder plug				
$\overline{}$	For incremental encoder interface	-	564264	NECC-A-S-S1G9-C2M
Plugs				
	For PROFIBUS interface	-	533780	FBS-SUB-9-WS-PB-K
10 10	For CANopen interface	-	533783	FBS-SUB-9-WS-CO-K
Direction of the second	For DeviceNet interface	-	525635	FBSD-KL-2X5POL
Ordering data – Assort	i		1 5 /	l -
	Description		Part no.	Туре
	Assortment of plugs for:			
	Motor controller CMMP-AS-C5/-C10-11A-P3-M0		☆ 552256	NEKM-C-3 ¹⁾
	Motor controller CMMP-AS-C5/-C10/-C15-11A-P3-M3			
	Interface CAMC-D-8E8A		569959	NEKM-C-5 ²⁾
- Aller	Motor controller CMMP-AS-C2/-C5-3A-M0		☆ 1659228	NEKM-C-7 ¹⁾
	Motor controller CMMP-AS-C2/-C5-3A-M3			
	Safety module CAMC-G-S1		☆ 1660640	NEKM-C-8 ³⁾
	Motor controller CMMP-ASM0			
	Safety module CAMC-G-S3		1660937	NEKM-C-9 ⁴⁾

- $1) \quad \text{Plugs are included in the scope of delivery of the motor controller CMMP-AS-...-M0, CMMP-AS-...-M3}$
- 2) Plugs are included in the scope of delivery of the plug-in card CAMC-D-8E8A
- Plug is included in the scope of delivery of the plug-in card CAMC-G-S1
 Plug is included in the scope of delivery of the motor controller CMMP-AS-...-M0
- 4) Plug is included in the scope of delivery of the plug-in card CAMC-G-S3

Ordering data - EMC filter for servo motors EMME-AS

Data sheets → Internet: emme-as

For cable lengths ≥ 10 m, the use of the EMC filter is recommended to reduce EMC interference.

For encoder cables \geq 10 m, the filter is included in the scope of delivery of the cable.

	Degree of protection	Ambient temperature	Part no.	Туре
£	IP30	−40 +80°C	4825847	CAMF-C5-FC
	(in mounted state)			

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Ordering data – Braking resistors					Data sheets → Internet: cacr
	For type	Resistance value $[\Omega]$	Nominal power [W]	Part no.	Туре
CACR-LE2					
	CMMP-AS-C2-3A	50	200	2882342	CACR-LE2-50-W500 ¹⁾
	CMMP-AS-C5-3A	72	200	1336611	CACR-LE2-72-W500
CACR-KL2					
Man.	CMMP-AS-C5-11A-P3	67	720	1336617	CACR-KL2-67-W1800
	CMMP-AS-C10-11A-P3	40	800	2882343	CACR-KL2-40-W2000 ¹⁾
	CMMP-AS-C15-11A-P3				

1) Recommended braking resistor

Ordering data – Mains filter						
	For type	Operating voltage	Input current	Dimensions	Part no.	Туре
		[V]	[A]	[mm]		
	CMMP-AS-C15-11A-P3	520/300	16	Length: 230 Width: 50 Height: 70	3947275	CADF-C15-11A-P3

- Note
Regardless of the length of the motor cable, the mains filter is mandatory for compliance with the CE and EN standards.

Ordering data — Software and documentation					
	Description	→ Internet			
	The following descriptions are available on the Festo website: Hardware: mounting and installation of all variants Functions: instructions on commissioning with FCT + functional description FHPP: control and parameterisation of the motor controller via the FHPP profile DS402: control and parameterisation of the motor controller via the device profile CiA 402 (DS402) CAM editor: cam disc functionality (CAM) of the motor controller Safety module: functional safety engineering for the motor controller with the safety function STO	www.festo.com/net/SupportPortal			

Ordering data – Software and documentation for the cam editor					
	Description	Part no.	Туре		
	Software package contains: CD-ROM With user documentation in de, en, es, fr, it, ru, zh With additional functions for the cam disc functionality The software package is not included in the scope of delivery	570903	GSPF-CAM-MC-ML		

Festo - Your Partner in Automation





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